

Randomized Subspace Newton Method for Unconstrained Non-Convex Optimization

PRAIRIE -RIKEN Workshop

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Overview

- 1 Introduction
- 2 Global convergence
- 3 Local convergence
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- 5 Summary

The gist

Non-convex unconstrained minimization

$$\min_{x \in \mathbb{R}^n} f(x),$$

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where $P \in \mathbb{R}^{s \times n}$ is a **random matrix**.

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where $P \in \mathbb{R}^{s \times n}$ is a **random matrix**.

- Can we speed up the computation time?
- Global and local convergence properties?

Previous works

Random Subspace Newton (RSN) [Gower et al., 2019] (f is convex)

By computing the Newton direction on the function $u \mapsto f(x_k + P_k^\top u_k)$, we obtain $u_k = -(P_k \nabla^2 f(x_k) P_k^\top)^{-1} P_k \nabla f(x_k)$, hence

$$x_{k+1} = x_k - t_k P_k^\top (P_k \nabla^2 f(x_k) P_k^\top)^{-1} P_k \nabla f(x_k).$$

They prove global sub-linear convergence and local linear convergence if f is strongly convex.

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- [Hanzely et al., 2020]: Cubically-regularized subspace Newton method.
- [Kovalev et al., 2020]: random subspace version of the BFGS method.
- [Roberts and Royer, 2022]: probabilistic direct-search method in reduced random spaces (non-convex problems). The authors prove sub-linear convergence.

Our work

Based on regularized Newton method (RNM) for the unconstrained non-convex optimization [Ueda and Yamashita, 2010], we propose the randomized subspace regularized Newton method (RS-RNM):

$$d_k = -P_k^\top (P_k \nabla^2 f(x_k) P_k^\top + \eta_k I_s)^{-1} P_k \nabla f(x_k),$$
$$x_{k+1} = x_k + t_k d_k,$$

where η_k is defined to ensure $P_k \nabla^2 f(x_k) P_k^\top + \eta_k I_s \succ 0$ and t_k satisfies Armijo's rule.

Our work

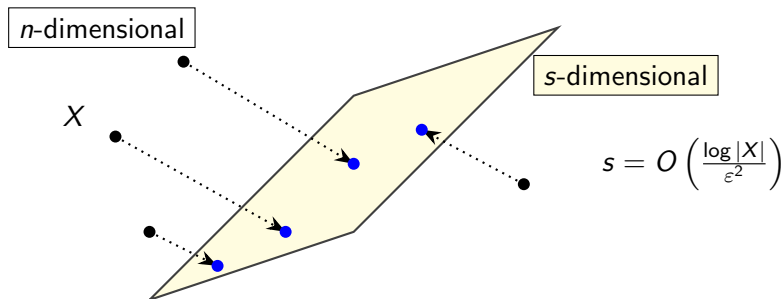
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- In [Ueda and Yamashita, 2010] the authors prove global sub-linear convergence and local quadratic convergence under local-error bound condition.
- Can we extend these results to the random subspace setting ?

What is Random Projection



Random Projection

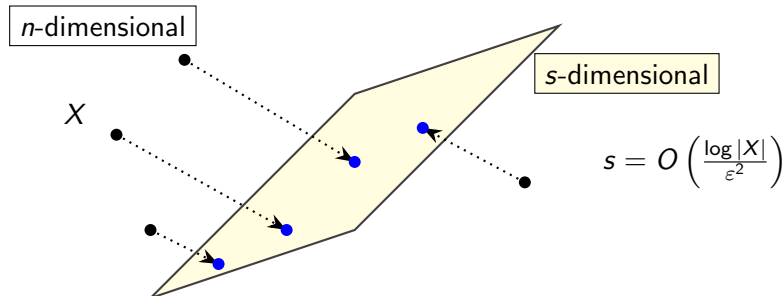
Lemma JLL

Let $P \in \mathbb{R}^{d \times n}$, $P_{ij} \sim N(0, 1/s)$, i.i.d..

Then for any $x \in \mathbb{R}^n$ and $\varepsilon \in (0, 1)$, we have

$$\text{Prob} [(1 - \varepsilon)\|x\|_2^2 \leq \|Px\|_2^2 \leq (1 + \varepsilon)\|x\|_2^2] \geq 1 - 2 \exp(-\mathcal{C}\varepsilon^2 s),$$

where \mathcal{C} is an absolute constant.



Concentration inequality for random matrices

$$P \in \mathbb{R}^{s \times n}$$

Proposition

There exists a constant $C_1 > 0$ such that:

$$\left\| \frac{1}{n} P P^T - I_s \right\| \leq C_1 \frac{s}{n},$$

holds with probability at least $1 - 2 \exp(-s)$.

Why is it useful ?

Remember that

$$d_k = -P_k^\top (P_k \nabla^2 f(x_k) P_k^\top + \eta_k I_s)^{-1} P_k \nabla f(x_k),$$

Why is it useful ?

Remember that

$$d_k = -P_k^\top (P_k \nabla^2 f(x_k) P_k^\top + \eta_k I_s)^{-1} P_k \nabla f(x_k),$$

Therefore, with high probability,

$$d_k = 0 \quad \iff \quad \nabla f(x_k) = 0.$$

Algorithm 1 Randomized subspace regularized Newton method (RS-RNM)

input: $x_0 \in \mathbb{R}^n$, $\gamma \geq 0$, $c_1 > 1$, $c_2 > 0$, $\alpha, \beta \in (0, 1)$

1: $k \leftarrow 0$

2: **repeat**

3: sample a random matrix: $P_k \sim$ Gaussian matrix $\mathcal{N}(0, 1/s)^{s \times n}$

4: compute the regularized sketched hessian:

$$M_k = P_k \nabla^2 f(x_k) P_k^\top + c_1 \Lambda_k I_s + c_2 \|\nabla f(x_k)\|^\gamma I_s, \text{ where } \Lambda_k = \max(0, -\lambda_{\min}(P_k \nabla^2 f(x_k) P_k^\top))$$

5: compute the search direction: $d_k = -P_k^\top M_k^{-1} P_k \nabla f(x_k)$

6: apply the backtracking line search with Armijo's to compute $l_k \geq 0$ such that (1) holds. Set $t_k = \beta^{l_k}$, $x_{k+1} = x_k + t_k d_k$ and $k \leftarrow k + 1$

7: **until** the stopping criteria is satisfied

8: **return** the last iterate x_k

$$f(x_k) - f(x_k + \beta^{l_k} d_k) \geq -\alpha \beta^{l_k} g_k^\top d_k. \quad (1)$$

Global convergence

Assumption (1)

The level set of f at the initial point x_0 is compact, i.e., $\Omega := \{\mathbb{R}^n : f(x) \leq f(x_0)\}$ is compact.

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Assumption (2)

- 1 $\gamma \leq 1/2$,
- 2 $\alpha \leq 1/2$,
- 3 There exists $L_H > 0$ such that

$$\|\nabla^2 f(x) - \nabla^2 f(y)\| \leq L_H \|x - y\|, \quad \forall x, y \in \Omega + B(0, r_1),$$

where $r_1 := \frac{CU_g^{1-\gamma} n}{c_2 S}$, and $\|\nabla f(x_k)\| \leq U_g$.

Global convergence

Let

$$t_{\min} = \min \left(1, \frac{\beta c_2^2 s^2}{c^2 L_H U_g^{1-2\gamma} n^2} \right) \quad p = \frac{\alpha t_{\min}}{2C(1 + c_1) \frac{n}{s} U_H + 2c_2 U_g^\gamma}.$$

Theorem

Suppose that Assumptions (1) and (2) hold. Let

$$m = \left\lceil \frac{f(x_0) - f^*}{p\epsilon^2} \right\rceil + 1$$

Then, with probability at least $1 - 2m \left(\exp(-\frac{c_0}{4}s) - \exp(-s) \right)$, we have

$$\sqrt{\frac{f(x_0) - f^*}{mp}} \geq \min_{k=0,1,\dots,m-1} \|\nabla f(x_k)\|.$$

$O(\epsilon^{-2})$ complexity: same that [Ueda and Yamashita, 2010].

Success probability

We want $1 - 2m \left(\exp\left(-\frac{c_0}{4}s\right) - \exp(-s) \right)$ as close to one as possible.

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Assume that $\|x_0 - x^*\| \leq \bar{C}\sqrt{n}$ for some constant $\bar{C} > 0$, then for some constant $\hat{C} > 0$,

$$m \leq \hat{C} \frac{n^{9/2}}{\varepsilon}.$$

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By taking $s = D \log(n)$, for $D > 9/2$ ensure $1 - 2m \left(\exp(-\frac{c_0}{4}s) - \exp(-s) \right)$ tends to 1.

Local convergence

Assume that $\{x_k\}$ converge to a strict local minima \bar{x} . We show that

- the sequence $\{f(x_k)\}$ converges locally linearly to $f(\bar{x})$
- when f is strongly convex, we cannot aim at local super-linear convergence using random subspace.

Local convergence: assumptions

Assumption (2')

In a neighborhood of \bar{x} , we have

$$\|\nabla^2 f(x) - \nabla^2 f(y)\| \leq L_H \|x - y\|.$$

Assumption (3)

We have that $s = o(n)$, that is, $\lim_{n \rightarrow +\infty} \frac{s}{n} = 0$.

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Assumption (4)

We assume that

- 1 *There exists $\sigma \in (0, 1)$ such that $r = \text{rank}(\nabla^2 f(\bar{x})) \geq \sigma n$*
- 2 *There exists $\rho \in (0, 3)$ and \tilde{C} such that in a neighborhood of \bar{x} , $f(x_k) - f(\bar{x}) \geq \tilde{C} \|x_k - \bar{x}\|^\rho$ holds.*

Proposition 1

Let $0 < \varepsilon_0 < 1$. Then under Assumptions (3) and (4.1) there exists $n_0 \in \mathbb{N}$ (which depends only on ε_0 and σ) and a neighborhood $B^* \subseteq \bar{B}$ such that if $n \geq n_0$, for any $x \in B^*$,

$$P \nabla^2 f(x) P^\top \succeq \frac{(1 - \varepsilon_0)^2 n}{2s} \sigma \bar{\lambda} I_s \quad \bar{\lambda} = \lambda_r(\bar{x})/2$$

holds with probability at least $1 - 6 \exp(-s)$.

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PL inequality

There exists $n_0 \in \mathbb{N}$ (which depends only on ε_0 and σ) and neighborhoods $\hat{B} \subset B^*$ and B_0 (a neighborhood of $0 \in \mathbb{R}^s$) such that if $n \geq n_0$, for any $x \in \hat{B}$,

$$\|P\nabla f(x)\|^2 \geq \frac{(1 - \varepsilon_0)^2 n}{s} \sigma \bar{\lambda} \left(f(x) - \min_{u \in B_0} f(x + P^\top u) \right)$$

holds with probability at least $1 - 6 \exp(-s)$.

Proposition 2

Under Assumptions (1),(2') and (4). there exists $0 < \kappa < 1$, $k_0 \in \mathbb{N}$, $n_0 \in \mathbb{N}$, and $\bar{C} > 0$ such that if $n \geq n_0$, $k \geq k_0$, we have with probability $1 - 6(\exp(-s) + \exp(-\frac{C_0}{4}s))$:

$$f(x_k) - \min_{u \in B_0} f(x_k + P_k^\top u) \geq \bar{C}(f(x_k) - f(\bar{x})).$$

Local convergence: Theorem 1

Theorem

Under Assumptions (1),(2'),(3) and (4), there exists $0 < \kappa < 1$, $k_0 \in \mathbb{N}$, and $n_0 \in \mathbb{N}$ such that if $n \geq n_0$, $k \geq k_0$, then

$$f(x_{k+1}) - f(\bar{x}) \leq \kappa(f(x_k) - f(\bar{x})).$$

holds with probability at least $1 - 6(\exp(-s) + \exp(-\frac{C_0}{4}s))$.

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Theorem

Under Assumptions (1),(2'),(3) and (4), there exists $0 < \kappa' < 1$, $s_0 \in \mathbb{N}$, $k_0 \in \mathbb{N}$, and $n_0 \in \mathbb{N}$ such that if $n \geq n_0$, $k \geq k_0$, then

$$\mathbb{E}[f(x_{k+1}) - f(\bar{x})] \leq \kappa' \mathbb{E}[f(x_k) - f(\bar{x})].$$

holds if $s \geq s_0$.

Super-linear convergence?

Assumption (5)

We assume that

$$(C + 2)^2 s < n.$$

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Theorem

Under Assumptions (2') and (5), if f is locally strongly convex around \bar{x} . There exists a constant $c > 0$ such that for k large enough,

$$\|x_{k+1} - \bar{x}\| \geq c \|x_k - \bar{x}\|$$

holds with probability at least $1 - 2 \exp(-\frac{C_0}{4}) - 2 \exp(-s)$.

Super-linear convergence?

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Theorem

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$$\|x_{k+1} - \bar{x}\| \geq c \|x_k - \bar{x}\|$$

holds with probability at least $1 - 2 \exp(-\frac{C_0}{4}) - 2 \exp(-s)$.

We deduce from the theorem and the assumptions that there exists a constant c' such that

$$f(x_{k+1}) - f(\bar{x}) \geq c'(f(x_k) - f(\bar{x})),$$

with probability at least $1 - 2 \exp(-\frac{C_0}{4}) - 2 \exp(-s)$.

Theorem

Under Assumptions (2') and (5), if f is locally strongly convex around \bar{x} . There exists a constant $c' > 0$ such that for k large enough, and s greater than some constant,

$$\mathbb{E}[\|x_{k+1} - \bar{x}\|] \geq c' \mathbb{E}[\|x_k - \bar{x}\|].$$

Numerical experiments: Support vector regression

Data: $\forall i \leq m, (x_i, y_i) \in \mathbb{R}^n \times \{0, 1\}$, we aim minimizing sum of a loss function and a regularizer

$$f(w) = \frac{1}{m} \sum_{i=1}^m \ell(y_i - x_i^\top w) + \lambda \|w\|^2.$$

- Internet advertisements dataset from UCI repository [Dua and Graff, 2017] processed so that the number of instances is $m = 600$ and $n = 1500$.
- Comparison with Gradient Descent (GD) and Regularized Newton Method (RNM)
- Step sizes are all determined by Armijo backtracking line search
- The parameters are fixed as follows:

$$c_1 = 2, c_2 = 1, \gamma = 0.5, \alpha = 0.3, \beta = 0.5, s \in \{100, 200, 400\}.$$

Loss function

$$\ell(t) = \frac{2t^2}{t^2 + 4}$$

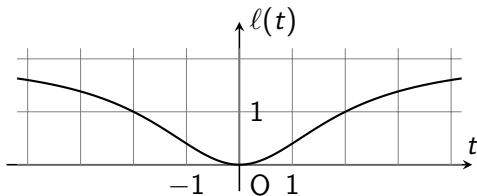


Figure: The robust loss functions.

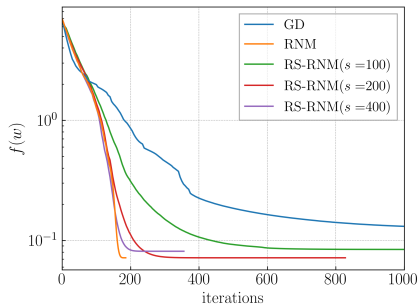


Figure: iterations versus $f(w)$ (\log_{10} -scale)

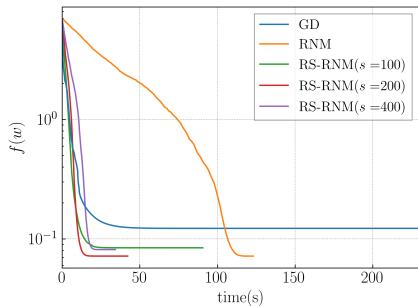


Figure: time versus $f(w)$ (\log_{10} -scale).

Future work

Can we find a second order subspace algorithm with local superlinear convergence ? Full paper: "T. Fuji, P.L. Poirion, A. Takeda, **Randomized**

subspace regularized Newton method for unconstrained non-convex optimization. arXiv:2209.04170, (2022)"

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